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## Summary of Commands

<b>A</b> –Acceleration	<b>LF</b> –Line Feed	<b>RV</b> –Revision Level
<b>B</b> –Buffer Status	<b>MC</b> –Mode Continuous	<b>S</b> –Stop
<b>BCDG</b> –Buffered Configure Derivative Gain	<b>MN</b> –Mode Normal	<b>SN</b> –Scan
<b>BCIG</b> –Buffered Configure Integral Gain	<b>MPA</b> –Mode Position Absolute	<b>SS</b> –Software Switch Function Status
<b>BCIL</b> –Buffered Configure Integral Limit	<b>MPI</b> –Mode Position Incremental	<b>SSA</b> –RS-232C Echo Control
<b>BCPE</b> –Buffered Configure Position Error	<b>N</b> –End of Loop	<b>SSC</b> –Output #1 on In Position
<b>BCTG</b> –Buffered Configure Derivative Sampling Period	<b>O</b> –Output	<b>SSE</b> –Enable/Disable Communication Error Checking
<b>BS</b> –Buffer Size Status	<b>OFF</b> –Servo Disable	<b>SSG</b> –Clear/Save the Command Buffer on Limit
<b>CDG</b> –Configure Derivative Gain	<b>ON</b> –Servo Enable	<b>SSH</b> –Clear/Save Command Buffer on Stop
<b>CEW</b> –Configure In Position Error Window	<b>OS</b> –Report Homing Function Set-Ups	<b>ST</b> –Shutdown
<b>CIG</b> –Configure Integral Gain	<b>OSA</b> –Define Active State of End-of-Travel Limits	<b>T</b> –Time Delay
<b>CIL</b> –Configure Integral Limit	<b>OSB</b> –Back Up To Home	<b>TR</b> –Wait For Trigger
<b>CIT</b> –Configure In Position Time	<b>OSC</b> –Define Active State of Home Switch	<b>U</b> –Pause and Wait for Continue
<b>CPE</b> –Configure Maximum Position Error	<b>OSD</b> –Enable Encoder Z Channel for Home	<b>V</b> –Velocity
<b>CPG</b> –Configure Proportional Gain	<b>OSH</b> –Reference Edge of Home Switch	<b>XC</b> –Sequence Checksum
<b>CR</b> –Carriage Return	<b>PR</b> –Report Commanded Position	<b>XD</b> –Sequence Definition
<b>CTG</b> –Configure Filter Time Constant	<b>PS</b> –Pause	<b>XE</b> –Sequence Erase
<b>D</b> –Distance	<b>PX</b> –Report Absolute Encoder Position	<b>XP</b> –Set Power-up Sequence Mode
<b>DPA</b> –Display Position Actual	<b>PZ</b> –Set Absolute Counter to Zero	<b>XQ</b> –Sequence Interrupted Run Mode
<b>DPE</b> –Display Position Error	<b>”</b> –Quote	<b>XR</b> –Run a Sequence
<b>DVA</b> –Display Velocity Actual	<b>Q1</b> –Enter Velocity Profiling Mode	<b>XRP</b> –Sequence Run With Pause
<b>E</b> –Enable Communications	<b>Q0</b> –Exit Velocity Profiling Mode	<b>XSD</b> –Sequence Status Definition
<b>ER</b> –Encoder Resolution	<b>R</b> –Request Indexer Status	<b>XSP</b> –Sequence Status Power-up
<b>F</b> –Disable Communications	<b>RA</b> –Limit Switch Status Report	<b>XSR</b> –Sequence Status Run
<b>G</b> –Go	<b>RB</b> –Loop, Pause, Shutdown, Trigger Status Report	<b>XSS</b> –Sequence Status
<b>GH</b> –Go Home	<b>RC</b> –Homing Status Report	<b>XT</b> –Sequence Termination
<b>^H</b> –Delete	<b>RFS</b> –Return Servo Gains to Factory Settings	<b>XU</b> –Upload Sequence
<b>H</b> –Set Direction	<b>RM</b> –Rate Multiplier in Velocity Streaming Mode	<b>Y</b> –Stop Loop
<b>IN</b> –Set Input Functions	<b>RSE</b> –Report Servo Errors	<b>Z</b> –Reset
<b>IS</b> –Input Status		<b>#</b> –Address Numbering
<b>K</b> –Kill		<b>%</b> –Reset Communication
<b>L</b> –Loop		
<b>LD</b> –Limit Disable		

