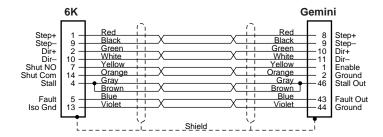
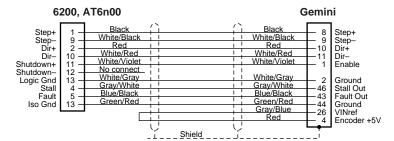
6K Connections to Gemini Drive



6200 Connections to Gemini Drive



Protective Circuits

Short Circuit Protection Inrush Current Protection Drive Overtemperature Protection Undervoltage Protection Regeneration Protection

Environmental Specifications

Operating Temperature Still Air: 45°C (113°F) Moving Air: 50°C (122°F)

Minimum: 0°C (32°F)

-40°C - 85°C (-40°F - 185°F) Storage Temperature: 0 - 95%, non-condensing

Humidity:

Troubleshooting

numbered 1 to n, from left to right):

(cleared with CERRLG).

TASX

TCS If TASX bit #7 or bit #28 is set, you can identify

Bit #6 indicates status of Enable input ("1" = OK TINO

TOUT

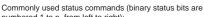
You must configure all motor parameters. Be sure to follow the drive configuration procedure (see Chapter 2 Installation).

Any fault condition causes the drive to shut down.

Use one of three methods to reset the drive (all command settings are remembered after reset):

Issue the RESET command. Momentarily close the Reset input. Cycle power to the drive.





TERRLG Error log reports the last 10 error conditions

TAS General report, including fault conditions.

Additional report of conditions not covered with

the cause with TCS.

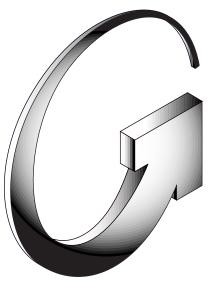
TIN Status of digital inputs, including end-of-travel

inputs.

Status of digital outputs.

The drive can not be enabled (DRIVE1) unless the Enable input is grounded and the Reset input is not grounded.





Gemini GT Stepper Drive

Compumotor Division Parker Hannifin Corporation p/n 88-017777-01 A (effective September 22, 1999)



To configure all drive parameters, connect a PC or HPC to this port. Use Motion Planner or Pocket Motion Planner for drive

RS-232/485 Connector – Configuration Port

If drive is faulted or disabled, relay will open. (Typical use: control of motor brake.) Relay rating: 5A at 24VDC or **RELAY N.O.** 120VAC. When drive is enabled, it holds relay closed. +24VDC provides keep alive power to Drive Keep Alive Power: RS-232 Connections 95 - 132VAC .0 ,0 .0 .0 +24VDC/Relay Connector Motor Cable Rx Tx Gnd GT-L5/8 N C Ξ Drive terminals: #8 (M4) Mating terminals: spade fork, 0.325" maximum width. Motor Wires **Motor Output Connections** Earth ₽ P ₽ Drive terminals: Mating terminals: Male Pins RELAY COM Drive 24V RTN +24V DC (RDB) (TDB) Terminals RS-485 Connections (RDA) (TDA) 95 - 132VAC #8 (M4). spade fork, 0.325" maximum width. Rx- Tx-AC Input Connections Tx+ Gnd • • • • • GT-U5/8 Connect jumper for 120VAC operations 190 – 264VAC **L1** ONO LZ/N V DBL BS-X3ZK8S STEPPER RELAY COM RELAY N.O. -MOTOR -1 L120V Z → ATN ⊕ **₹** ₩ ₽+ P (3) € Multiple Drive Connections € € For multiple drives, use a Left Right Off Yel Red (flash) Off Grn (flash) Yel (flash) Left Off Green/Red Yellow/Green Grn Grn Grn Red reserved reserved reserved Output Ground Output 4 Output Ground Output Ground Output Ground Output Cound Input Ground reserved reserved reserved reserved input Ground reserved reserved reserved reserved reserved input Ground input Ground input Ground input Ground input Ground input Ground 8 Grn 읔 읔 Grn (flash) Yel/Grn (flash) Autorun mode 50 Pin DRIVEI/O Connector Incoming steps (variable rate) Programming flash memory Drive ready Drive faulted Drive not enabled Keep alive mode Initialization Indicated State* Awaiting flash download 25 Analog Ground 28 ± 10V Vel Cmd 29 ± 10V Vel Cmd 29 ± 10V Vel Cmd 20 ± 10V Vel Cmd 21 Analog Output B 21 Analog Output B 21 Analog Output A 22 Brights Ground 23 reserved 24 Reserved 25 Epp- Out 27 ZY+ 28 Step-YCW-/BX27 Digital Ground 26 Encoder +5V 27 Digital Ground 28 Reset 29 Digital Ground 31 Reset 20 Enable

single point safety earth

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