

TQ10X Summary of Commands

AB	A B BCDGD BCIG BCIL BCPE BCPG BCTG BS	Acceleration Buffer Status Buffered Configure Derivative Gain Buffered Configure Integral Gain Buffered Configure Integral Limit Buffered Configure Position Error Buffered Configure Proportional Gain Buffered Configure Derivative Sampling Period Buffer Size Status	P	PR PS PX PZ	Report Commanded Position Pause Report Absolute Encoder Position Set Absolute Counter to Zero
CD	C CDG CEW CIG CIL CIT CPE CPG CR CTG D DPA DPE DVA	Continue Configure Derivative Gain Configure in Position Error Window Configure Integral Gain Configure Integral Limit Configure in Position Time Configure Maximum Position Error Configure Proportional Gain Carriage Return Configure Derivative Sampling Period Distance Display Position Actual Display Position Error Display Velocity Actual	QR	" Q1 Q0 R RA RB RC RFS RM RSE RV	Quote Enter Velocity Profiling Mode Exit Velocity Profiling Mode Request Indexer Status Limit Switch Status Report Loop, Pause, Shutdown, Trigger Status Report Homing Status Report Return Servo Gains to Factory Settings Rate Multiplier in Velocity Streaming Mode Report Servo Errors Revision Level
EFG	E ER F G GH	Enable Communications Encoder Resolution Disable Communications Go Go Home	STUV	S SN SS SSA SSC SSG SSH ST T TR U V	Stop Scan Software Switch Function Status RS-232C Echo Control Output #1 on In Position Clear/Save Command Buffer on Limit Clear/Save Command Buffer on Stop Shutdown Time Delay Wait for Trigger Pause and Wait for Continue Velocity
HIJKL	H H IN IS K L LD LF	Delete Set Direction Set Input Functions Input Status Kill Loop Limit Disable Line Feed	XYZ#	XC XD XE XP XQ XR XRP XSD XSP XSR XSS XT XU Y Z #	Sequence Checksum Sequence Definition Sequence Erase Set Power-up Sequence Mode Sequence Interrupted Run Mode Run a Sequence Sequence Run with Pause Sequence Status Definition Sequence Status Power-up Sequence Status Run Sequence Status Sequence Termination Upload Sequence Stop Loop Reset Address Numbering
MN	MC MN MPA MPI N	Mode Continuous Mode Normal Mode Position Absolute Mode Position Incremental End of Loop	O	O OFF ON OS OSA OSB OSC OSD OSH	Output Servo Disable Servo Enable Report Homing Function Set Ups Define Active State of End-of-Travel Limits Back Up to Home Define Active State of Home Switch Enable Encoder Z-Channel for Home Reference Edge of Home Switch

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